

# Application of Optimal Mass Transportation to Medical Image Analysis



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April 29, 2022

# Outline

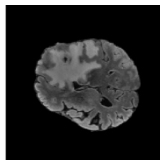
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- 2 Related work
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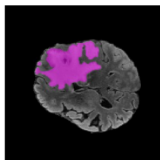
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# Introduction

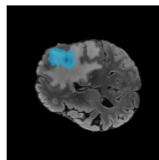
- RSNA-ASNR-MICCAI Brain Tumor Segmentation (BraTS)



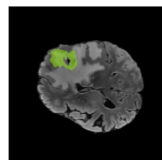
Flair



Whole Tumor



Tumor Core



Enhance Tumor

tumor	label
WT	1, 2, 4
TC	1, 4
ET	4

Table 1: The label of WT, TC, and ET.

# Introduction

- 1 **Motivation:** reduce memory usage and keep global information
- 2 **Idea:** map irregular domain to regular domain
- 3 **Difficulty:** high conversion loss

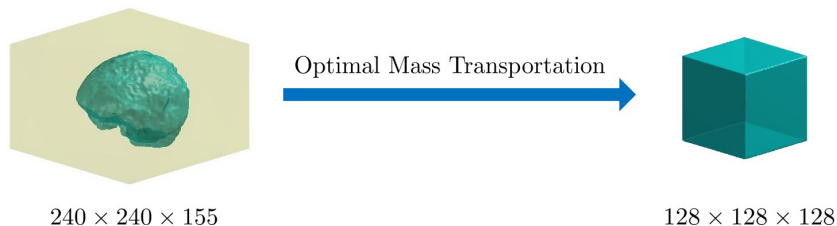


Figure 1: An illustration for the OMT

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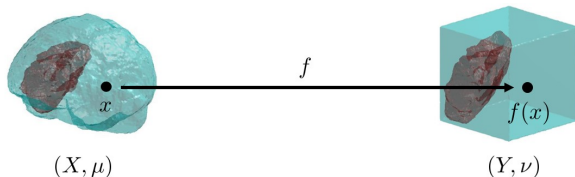
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# Optimal Mass Transportation

## OMT Problem

Let  $(X, \mu), (Y, \nu)$  be two measurable spaces which have the same total mass  $\int_X 1d\mu = \int_Y 1d\nu$ . Let  $\mathcal{F}$  be the set of measure-preserving maps and  $c : X \times Y \rightarrow [0, \infty]$  be a cost function of transportation. The OMT problem is to find a map  $f^* \in \mathcal{F}$  that minimizes the transportation cost

$$f^* = \arg \min_{f \in \mathcal{F}} \int_X c(x, f(x)) d\mu.$$



# Discrete OMT

## Definition (Discrete OMT Problem)

The discrete OMT problem with respect to  $\|\cdot\|_2$  can represent as

$$\mathbf{f}^* = \arg \min_{\mathbf{f} \in \mathbb{F}_{\mu_V}} \sum_{i=1}^{n_v} \|v_i - \mathbf{f}_i^*\|_2^2 \mu_V(v_i)$$

where the local measure at the vertex  $v$  is

$$\mu_V(v) = \frac{1}{4} \sum_{v \subset \tau, \tau \in \mathcal{T}(\mathcal{B})} \text{vol}(\tau) \cdot \rho(v)$$

and the space of mass-preserving map is

$$\mathbb{F}_{\mu_V} = \left\{ \mathbf{f} \in \mathbb{R}^{n_v \times 3} \mid \mathbf{f} \text{ is the inducing matrix for a mass-preserving map } f : (\mathcal{B}, \mu_V) \rightarrow (\mathcal{C}, \text{vol}) \right\}.$$



# Discrete OMT

## OMT steps

- 1 Solve the **boundary map** by **projection gradient method**.
- 2 Solve the **interior map** by **homotopy method**.

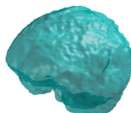
## Solving the boundary map by projection gradient method

## Definition (Spherical OMT Problem)

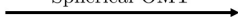
$$\mathbf{g}^* = \arg \min_{\mathbf{f} \in \mathbb{G}_{\mu_S}} \sum_{i=1}^{n_B} \|v_i - \mathbf{g}_i^*\|_2^2 \mu_S(v_i)$$

where the space of mass-preserving map is

$$\mathbb{G}_{\mu_S} = \left\{ \mathbf{g} \in \mathbb{R}^{n_B \times 3} \mid \mathbf{g} \text{ is the inducing matrix for a mass-preserving map } g : (\partial\mathcal{B}, \mu_S) \rightarrow (\mathbb{S}^2, \text{area}) \right\}$$


 $(\partial\mathcal{B}, \mu_S)$ 

Spherical OMT


 $(\mathbb{S}^2, \text{area})$

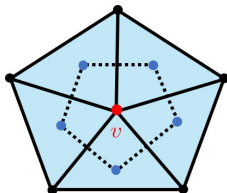
## Solving the boundary map by projection gradient method

## Definition (Spherical OMT Problem)

$$\mathbf{g}^* = \arg \min_{\mathbf{f} \in \mathbf{G}_{\mu_S}} \sum_{i=1}^{n_B} \|v_i - \mathbf{g}_i^*\|_2^2 \mu_S(v_i)$$

where the local measure at the vertex  $v$  as

$$\mu_S(v) = \frac{1}{3} \sum_{v \subset \tau, \tau \in \mathcal{F}(\partial \mathcal{B})} \text{area}(\tau) \cdot \rho(v).$$



# Solving the boundary map by projection gradient method

Let  $\mathcal{P}_*$  be a projection operator. Then  $\mathbf{g}^t$  can update by

$$\mathbf{g}^{t+1} = \mathcal{P}_{G_{\mu_S}}(\mathbf{g}^t - \eta^t \nabla C(\mathbf{g}^t))$$

where the cost function  $C(\mathbf{g}) = \sum_{i=1}^{n_B} \|v_i - \mathbf{g}_i^*\|_2^2 \mu_S(v_i)$  and the learning rate  $\eta$  is chosen by line search.

## Projection operator

- 1 Normalize to spherical  $g(v) \leftarrow \frac{g(v)}{\|g(v)\|_2}$ .
- 2 Compute the **spherical mass-preserving parameterization** with  $g$  as initial.
- 3 Adjust the optimal rotation by SVD.

# Solving the boundary map by projection gradient method

- 1 Compute the spherical OMT map  $g_1 : \partial\mathcal{B} \rightarrow \mathbb{S}^2$  with density  $\rho$ .
- 2 Compute the spherical OMT map  $g_2 : \partial\mathcal{C} \rightarrow \mathbb{S}^2$  with area-preserving.
- 3 Compose the map by  $g = g_2^{-1} \circ g_1$ .

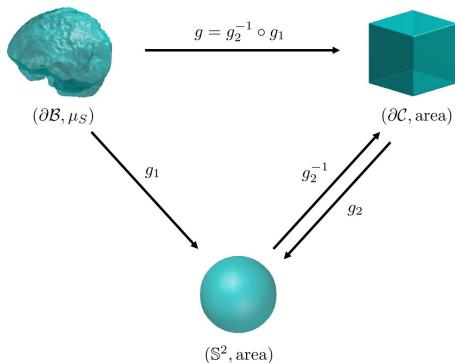


Figure 2: Compose the spherical OMT map

# Solving the interior map by homotopy method

Let  $0 = t_0 < t_1 < \dots < t_p = 1$  be the  $p$  piece of  $[0, 1]$  and

$$\mathbf{f}_B^{(k)} = (1 - t_k)V_B + t_k\mathbf{g}$$

be the homotopy of boundary map. We solve the interior map by

$$[L_V(f^{(k-1)})]_{L,I}\mathbf{f}_I^{(k)} = -[L_V(f^{(k-1)})]_{L,B}\mathbf{f}_B^{(k)}.$$

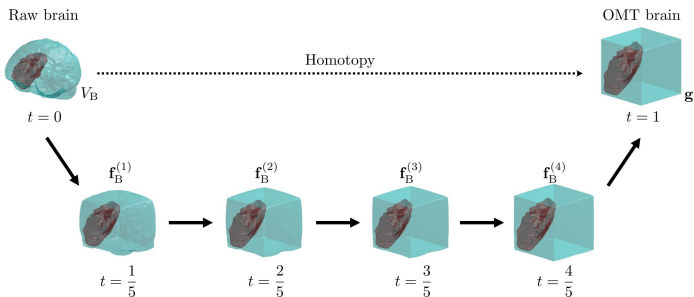


Figure 3: Homotopy flowchart

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# Two-Phase training process

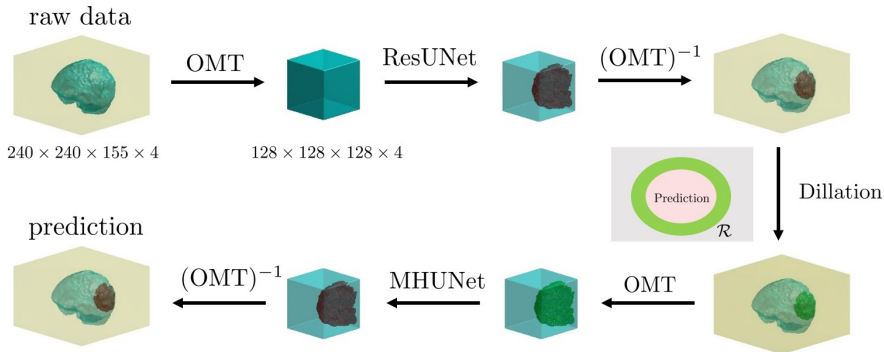


Figure 4: Two-Phase training flowchart



# Density function

Let  $I$  be the grayscale of flair, HE be the histogram equalization.

① **Phase 1 OMT density function:**

$$\rho_1(v) = \exp(\gamma \cdot \text{HE}(I(v))), v \in \mathcal{B}$$

② **Phase 2 OMT density function:**

$$\rho_2(v) = \begin{cases} \exp(\gamma \cdot \text{HE}(I(v))), & \text{if } v \in \mathcal{R} \\ 1.0, & \text{if } v \in \mathcal{B} \setminus \mathcal{R} \end{cases}$$

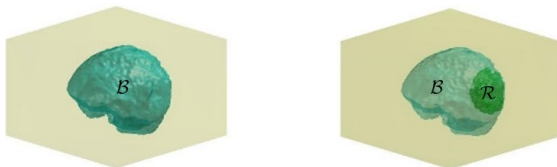


Figure 5: Region of density

# Model architecture

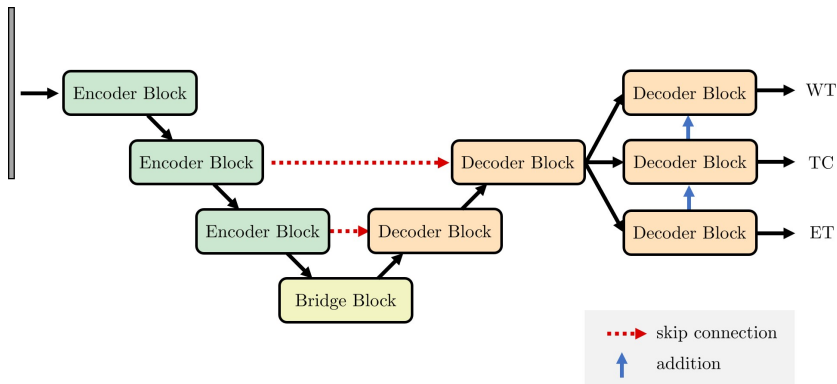


Figure 6: Multi-Head UNet (MHUNet) architecture

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# Conversion loss

Let  $Y$  be the ground truth,  $T : \mathcal{B} \rightarrow \mathcal{C}$  be the OMT map, and  $T^{-1} : \mathcal{C} \rightarrow \mathcal{B}$  be the inverse OMT map. We defined the conversion loss

$$1 - \frac{2|Y \cap (T^{-1} \circ T)(Y)|}{|Y| + |(T^{-1} \circ T)(Y)|}$$

Grid size	Phase 1			Phase 2		
	WT	TC	ET	WT	TC	ET
$112^3$	0.97%	1.10%	2.70%	0.13%	0.12%	0.33%
$128^3$	0.34%	0.38%	0.96%	0.02%	0.02%	0.05%

Table 2: Conversion loss of data.

## OMT data visualize

data	WT	TC	ET
raw data	6.49%	2.42%	1.45%
$128^3$ cube with $\gamma = 1.0$	13.47%	5.03%	3.04%
$128^3$ cube with $\gamma = 1.5$	18.27%	6.84%	4.14%
$128^3$ cube with $\gamma = 1.75$	20.93%	7.84%	4.75%
$128^3$ cube with $\gamma = 2.0$	23.72%	8.90%	5.40%

Table 3: Proportion of tumor in brain

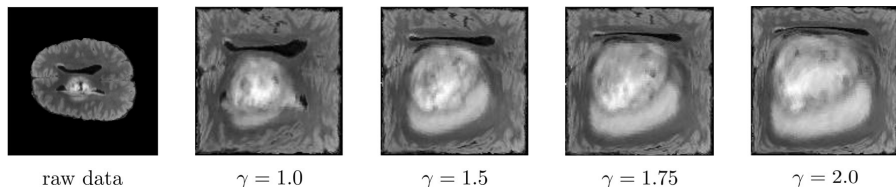


Figure 7: Case BraTS2021\_00003

# Validation result

Let  $P$ ,  $G$  be a prediction and ground truth. The dice similarity coefficient (DSC) is defined as

$$\text{DSC}(P, G) = \frac{2|P \cap G|}{|P| + |G|}$$

Model	WT	TC	ET
VNet	0.9318	0.9005	0.8691
UNet	0.9305	0.9023	0.8646
ResUNet	0.9307	0.9101	0.8602
MHUNet	<b>0.9321</b>	<b>0.9146</b>	<b>0.8683</b>

Table 4: DSC of validation dataset

# Test result

Model	WT	TC	ET
MDUNet	0.9196	0.8644	0.8277
MDUNet+TTA	<b>0.9201</b>	<b>0.8686</b>	<b>0.8308</b>

Table 5: DSC of testing dataset

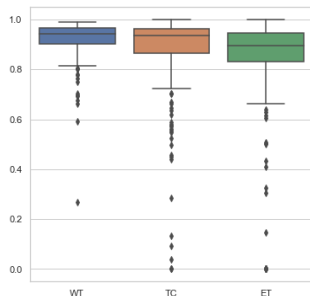


Figure 8: Box plot of DSC of testing dataset

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# Conclusion

- 1 OMT map an object from an irregular domain to a regular domain, which reduce memory usage and keep global information.
- 2 OMT can generate data augmentation by using the different parameters of density.
- 3 We propose the Two-Phase training process.

# Reference

- ① M.-H. Yueh, T.-M. Huang, T. Li, W.-W. Lin, and S.-T. Yau, “Projected gradient method combined with homotopy techniques for volume-measure-preserving optimal mass transportation problems,” *J. Sci. Comput.*, no. 64, 2021.
- ② W.-W. Lin, C. Juang, M.-H. Yueh, T.-M. Huang, T. Li, S. Wang, and S.-T. Yau, 3D Brain Tumor Segmentation Using a Two-Stage Optimal Mass Transport Algorithm, *Scientific Reports*, 11, 14686, 2021. <https://doi.org/10.1038/s41598-021-94071-1>
- ③ O. Ronneberger, P. Fischer, and T. Brox, “U-net: Convolutional networks for biomedical image segmentation,” in *International Conference on Medical image computing and computer-assisted intervention*. Springer, 2015, pp. 234–241.

THE END

# Thanks for listening!